wictotolic



Operating Instructions

Ultrasonic proximity switch with one switched output

zws-15/CE/OS zws-15/CD/OS zws-24/CD/OS zws-24/CE/OS zws-25/CD/OS zws-25/CE/OS zws-35/CD/OS zws-35/CE/OS zws-70/CD/OS zws-70/CE/OS

Product Description

The zws sensor offers a non-contact measurement of the distance to an object which must be positioned within the sensor's detection zone. The switched output is set in dependence of the adjusted detect distance.

Via the push-button, the detect distance and operating mode can be adjusted (teach-in). Two LEDs indicate operation and the state of the switched output.

Safety Notes

- Read the operating instructions prior
- Connection, installation and adjustment works may only be carried out by skilled personnel.
- No safety component in accordance with the EU Machine Directive

Proper use

zws ultrasonic sensors are used for non-contact detection of objects.



Fig. 1: Attachment with mounting plate

Installation

- Mount the sensor at the installation site with the aid of the enclosed mounting plate, s. Fig. 1. Maximum torque: 0.5 Nm
- Connect a connection cable to the M8 device plug, s. fig. 2.
- Avoid mechanical load on the connector

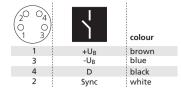


Fig. 2: Pin assignment with view onto sensor plua and colour coding of the microsonic connection cable

Start-Up

- Connect the power supply.
- Carry out the adjustment in accordance with the diagram.

Factory Setting

- Operation with one detect point
- Switched output on NOC
- Detect points at operating range

Three operating modes are available for the switched output:

- The switched output is set if the obiect falls below the set detect point.

The switched output is set if the obiect is within the set window mar-

■ Two-way reflective barrier The switched output is set if the ob-

Synchronization

You can synchronize as many sensors as you like.

■ Apply a square-wave signal to the sync-input with pulse width t_i and repetition rate t_p (see fig. 3 and technical data).

Any amount of sensors may be synchronized with this external synchronisation signal.

A high level on sync-input will deactivate the sensor.

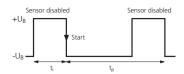


Fig. 3: External synchronization signal

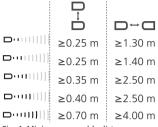


Fig. 4: Minimum assembly distances

Checking operation mode

■ In normal mode shortly press the push-button.

The green LED stops shining for one second, then it will show the current operating mode:

 $1 \times \text{ flashing } = \text{ operation with one}$ switching point

2 x flashing = window mode

3 x flashing = reflective barrier

After a break of 3 s the green LED shows the output function:

 $1 \times flashing = NOC$

 $2 \times flashing = NCC$

Maintenance

sensor surface.

- within which distance measurements are not possible.
- In the normal operating mode, an illuminated yellow LED signals the switched output is switched through.
- The standard sensor has no temperature compensation.
- If the object moves towards the

Operating modes

Operation with one detect point

■ Window mode

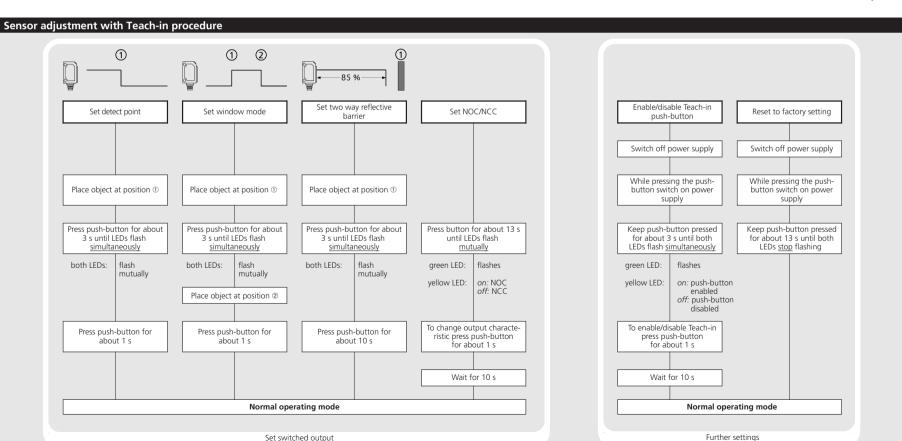
iect is between sensor and reflector.

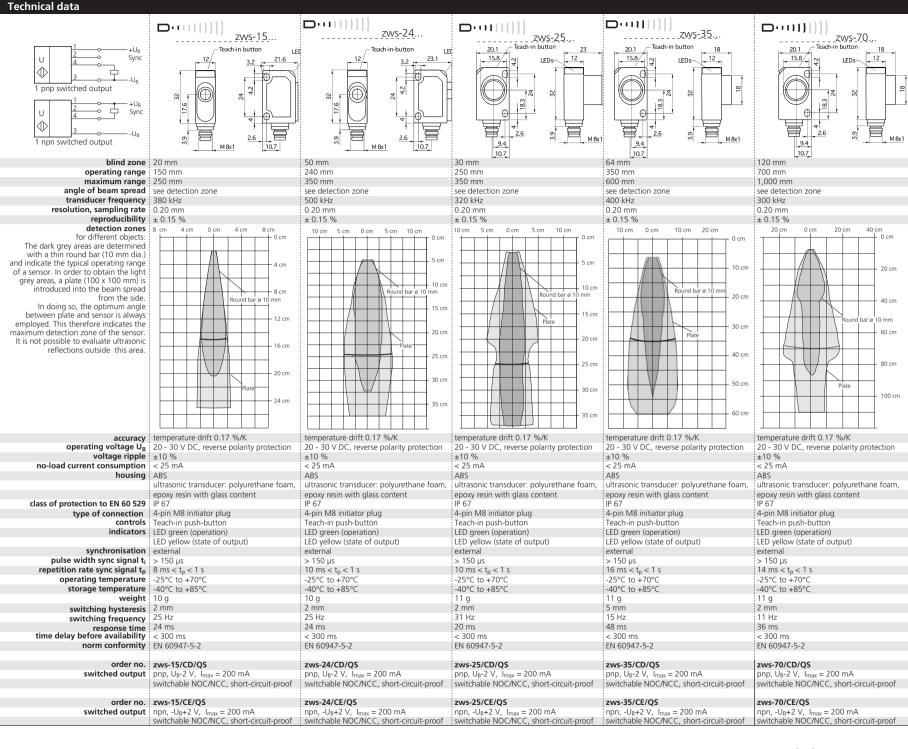
microsonic sensors are maintenancefree. In case of excess caked-on dirt we recommend cleaning the white

Notes

- The zws sensor has a blind zone.

- sensor, e.g. level control (method A) the detect point can be taught





to the actual distance at which the sensor has to switch the output. If the object to be sensed moves into the detection area from the

side (method B), the switching distance should be set 8-10 % further than the desired switch point to obtain a reliable object detection, see fig. 5.

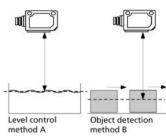


Fig. 5: Set the detect point for different directions of movement of the object

- In the »Two-way reflective barrier« operating mode, the object has to be within the range of 0-85 % of the set distance.
- If the push-button is not pressed for 10 minutes during the Teach-in setting, the settings made hitherto are deleted
- The sensor can be reset to its factory setting.

