

Product Description The zws sensor offers a non-contact measurement of the distance to an object which must be positioned

499The the sensor's detection zone The switching output is set in depen dence of the adjusted detect distance Via the push-button, the detect distance and operating mode can be adjusted (Teach-in). Two LEDs indicate operation and the state of the swit ching output.

## Safety Notes

- Read the operation manual prior to start-up.
Ultrasonic proximity switch with one switching output

| zws-15/CD/QS | zws-15/CE/QS |
| :--- | :--- |
| zws-24/CD/QS | zws-24//E/QS |
| zWs-25/CD/QS | zw-25/CE/QS |
| zws-35/CD/QS | zws-35/CE/QS |
| zws-70/CD/QS | zws-70/CE/QS |

## sonal and machine protection

 not permitted
## Use for intended purpose only

zWs ultrasonic sensors are used for non-contact detection of objects.

## Installation

$\rightarrow$ Mount the sensor at the installation site with the aid of the enclosed mounting plate (see Fig. 1). Maximum torque of attachment screw. $0,5 \mathrm{Nm}$
$\rightarrow$ Connect a connection cable to the M8 device plug.
$\rightarrow$ Avoid mechanical load on the connector.

## Start-Up

$\rightarrow$ Connect the power supply.
$\rightarrow$ Carry out the adjustment in accordance with Diagram 1


Fig. 1: Attachment with mounting plate
 2. Pin assignment with view onto sensor plug and colour coding of the microso nic connection cable

## Factory Setting

Ww sensors are delivered with the folowing settings:

- Operation with one switching point
- Switching output on NOC
- Switching point at operating range


## Operating modes

Three operating modes are available for the switching output:

- Operation with one switching point
The switching output is set if the object falls below the set switching point.
- Window mode

The switching output is set if the object is within the set window limits.

- Two-way reflective barrier The switching output is set if there s no object between sensor and reflector.


## Diagram 1: Set sensor parameters via Teach-in procedure



## Checking operating mod

$\rightarrow$ In normal operating mode shortly press the push-button. The green LED stops shining for one second, then it will show the current operating mode:

- $1 x$ flashing $=$ operation with one
$2 x$ flashing $=$ switching poin
- $3 x$ flashing $=$ reflective barrie

After a break of 3 s the green LED shows the output function:

- $1 x$ flashing $=$ NOC
- $2 x$ flashing $=$ NCC
- $3 x$ flashing $=$ NOC (twin)
- 4x flashing $=$ NCC (twin)


## Mutual Influencing and Synchro-

 nizationIf two or more sensors are mounted too close to one another and the minimum assembly distances (see Fig. 3) between the sensors are not reached they can influence one another. There are two methods available to avoid this.

- If only two sensors are operating, the twin mode can be selected at one of the two sensors via the sensor setting »Set NOC/NCC and twin mode«. The other sensor stays at the standard NOC/NCC setting. For the sensor in twin mode, response delay is slightly increased und therefore the switching frequency reduced.
- If more than two sensors are operating close to one another, the sensors can be synchronised by the accessory SyncBox2

|  | $\square$ |  |
| :--- | :---: | :---: |
| $\ldots-\ldots$ | $\square$ | $\square \square$ |
| zws-15... | $\geq 0.25 \mathrm{~m}$ | $\geq 1.30 \mathrm{~m}$ |
| zws-24... | $\geq 0.25 \mathrm{~m}$ | $\geq 1.40 \mathrm{~m}$ |
| zWs-25... | $\geq 0.35 \mathrm{~m}$ | $\geq 2.50 \mathrm{~m}$ |
| zWs-35... | $\geq 0.40 \mathrm{~m}$ | $\geq 2.50 \mathrm{~m}$ |
| zws-70... | $\geq 0.70 \mathrm{~m}$ | $\geq 4.00 \mathrm{~m}$ |

Fig. 3: Minimum assembly distances for Syn

## Maintenance

microsonic sensors are maintenancefree. In case of excess caked-on dirt we recommend cleaning the white sensor surface


Notes

- The zws sensor has a blind zone, within which distance measurements are not possible
- The sensor has no temperature compensation.
- In the normal operating mode, an illuminated yellow LED signals the switching output is switched through.
- In the »Set switching point - method A« Teach-in procedure the actual distance to the object is taught to the sensor as the switching point. If the object moves towards the sensor (e.g. with level control) then the taught distance is the level at which the sensor has to switch the output.
If the object to be scanned moves into the detection area from the side, the »Set switching point +8 \% - method B« Teach-in procedure should be used. In this way the switching distance is set $8 \%$ further than the actual measured distance to the object. This ensures a reliable switching distance even if the height of the objects varies slightly, see Fig. 4


Fig. 4: Set the switching point for different directions of movement of the object

- In the »Two-way reflective barrier« operating mode, the object has to be within the range of 0 to $85 \%$ of the set distance
- If the push-button is not pressed for 8 minutes during the Teach-in setting, the settings made until now are deleted.
This operation manual applies to zWs ensors from firmware version V3. The firmware version can be checked via Teach-in procedure »Set NOC/NCC and twin mode«. If the yellow LED flashes, this zws sensor has firmware V3 or higher.

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## Operation Manual

Ultrasonic proximity switch with one switching output

| zws-15/CD/QS | zws-15/CE/QS |
| :--- | :--- |
| zws-24/CD/QS | zws-24//E/QS |
| zWs-25/CD/QS | zw-25/CE/QS |
| zws-35/CD/QS | zws-35/CE/QS |
| zws-70/CD/QS | zws-70/CE/QS | $\begin{array}{ll}\text { zws-24/CD/QS } & \text { zws-24/CE/QS } \\ \text { zws-25/CD/QS } & \text { zws-25/CE/QS }\end{array}$ $\begin{array}{ll}\text { zws-25/CD/QS } & \text { zww-255/CE/QS } \\ \text { zws-35/CDDSS } & \text { zws-35/CE/QS }\end{array}$ zws-70/CD/QS

## Diagram 1: Set sensor parameters via Teach-in procedure



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## Use for intended purpose only

zWS ultrasonic sensors are used for non-contact detection of objects.

## Installation

$\rightarrow$ Mount the sensor at the installation site with the aid of the enclosed mounting plate (see Fig. 1). Maximum torque of attachment screw: $0,5 \mathrm{Nm}$
$\rightarrow$ Connect a connection cable to the M8 device plug.
$\rightarrow$ Avoid mechanical load on the connector.

## Start-Up

$\rightarrow$ Connect the power supply.
$\rightarrow$ Carry out the adjustment in accordance with Diagram 1.


Fig. 1: Attachment with mounting plate

Fig. 2: Pin assignment with view onto senso plug and colour coding of the microso nic connection cable

## Factory Setting

ws-sensors are delivered with the folowing settings:

- Operation with one switching point
- Switching output on NOC
- Switching point at operating range


## Operating modes

Three operating modes are available for the switching output:

- Operation with one switching point
The switching output is set if the object falls below the set switching point.
- Window mode

The switching output is set if the object is within the set window limits.

- Two-way reflective barrier The switching output is set if there is an object between sensor and reflector.


## Checking operating mode

$\rightarrow$ In normal operating mode shortly press the push-button. The green LED stops shining for one second, then it will show the current operating mode:

- $1 x$ flashing $=$ operation with one
$2 x$ flashing $=$ switching poin
- $3 x$ flashing $=$ reflective barrie

After a break of 3 s the green LED shows the output function:

- $1 x$ flashing = NOC
- $2 x$ flashing $=$ NCC


## Synchronisation

you can synchronise as many sensors as you like.
$\rightarrow$ Apply a square-wave signal to the sync-input with pulse width $t_{i}$ and repetition rate $t_{p}$ (Fig. 3 and technical data).
A high level on the sync input will disable the sensor.


Fig. 3: External synchronisation signal


Fig. 4: Minimum assembly distances for Sync

## Maintenance

microsonic sensors are maintenancefree. In case of excess caked-on dirt we recommend cleaning the white sensor surface.


## Notes

- The zws sensor has a blind zone, within which distance measurements are not possible.
- The standard sensor has no temperature compensation.
- In the normal operating mode, an illuminated yellow LED signals the switching output is switched through.
In the Teach-in procedure the actual distance to the object is taught to the sensor as the switching point. If the object moves towards the sensor (e.g. with level control) then the taught distance is the level at which the sensor has to switch the output. If the object to be scanned moves into the detection area from the side, an 8 to 10 \% greater distance should be set for reliable object de tection by the sensor, see Fig. 5

fig. 5: Set the switching point for different directions of movement of the object
- In the »Two-way reflective barrier« operating mode, the object has to be within the range of 0 to $85 \%$ of the set distance.
- If the push-button is not pressed for 10 minutes during the Teach-in setting, the settings made until now are deleted.
- The sensor can be reset to its factory setting, see »Further settings«, Diagram 1.

