# microsonic Product Description



**Operation Manual** 

Ultrasonic proximity switch with one switching output

zws-15/CE/QS zws-15/CD/QS zws-24/CE/QS zws-24/CD/QS zws-25/CD/QS zws-25/CE/QS zws-35/CD/QS zws-35/CE/QS zws-70/CD/QS zws-70/CE/QS

# Diagram 1: Set sensor parameters via Teach-in procedure

sonal and machine protection not permitted

## Use for intended purpose only

zws ultrasonic sensors are used for non-contact detection of objects.

#### Installation

The zws sensor offers a non-contact

measurement of the distance to an

object which must be positioned

within the sensor's detection zone.

The switching output is set in depen-

dence of the adjusted detect distance.

Via the push-button, the detect dis-

tance and operating mode can be

adjusted (Teach-in). Two LEDs indicate

operation and the state of the swit-

Read the operation manual prior

Connection, installation and ad-

ried out by expert personnel.

■ No safety component in ac-

iustment works may only be car-

cordance with the EU Machine

Directive, use in the area of per-

ching output.

Safety Notes

to start-up.

- → Mount the sensor at the installation site with the aid of the enclosed mounting plate (see Fig. 1). Maximum torque of attachment screw: 0,5 Nm
- → Connect a connection cable to the M8 device plug.
- → Avoid mechanical load on the connector.

#### Start-Up

- → Connect the power supply.
- → Carry out the adjustment in accordance with Diagram 1.

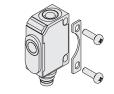


Fig. 1: Attachment with mounting plate

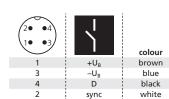


Fig. 2: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

# Factory Setting

zws sensors are delivered with the following settings:

- Operation with one switching point Switching output on NOC
- Switching point at operating range

#### **Operating modes**

Three operating modes are available for the switching output:

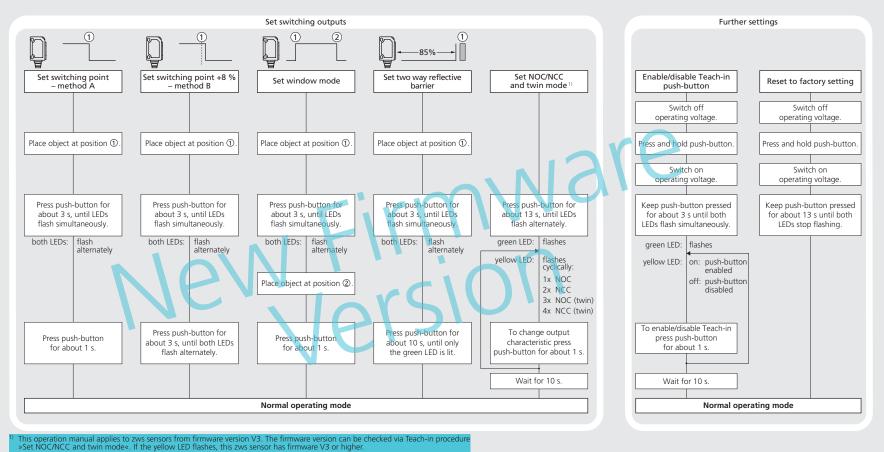
Operation with one switching point

The switching output is set if the object falls below the set switching point.

Window mode

The switching output is set if the object is within the set window limits.

Two-way reflective barrier The switching output is set if there is no object between sensor and reflector.



#### Checking operating mode

- → In normal operating mode shortly press the push-button. The green LED stops shining for one second, then it will show the current operating mode:
- 1x flashing = operation with one switching point
- 2x flashing = window mode
- 3x flashing = reflective barrier

After a break of 3 s the green LED shows the **output function**:

- 1x flashing = NOC
- 2x flashing = NCC
- **\blacksquare** 3x flashing = NOC (twin)
- 4x flashing = NCC (twin)

### Mutual Influencing and Synchronization

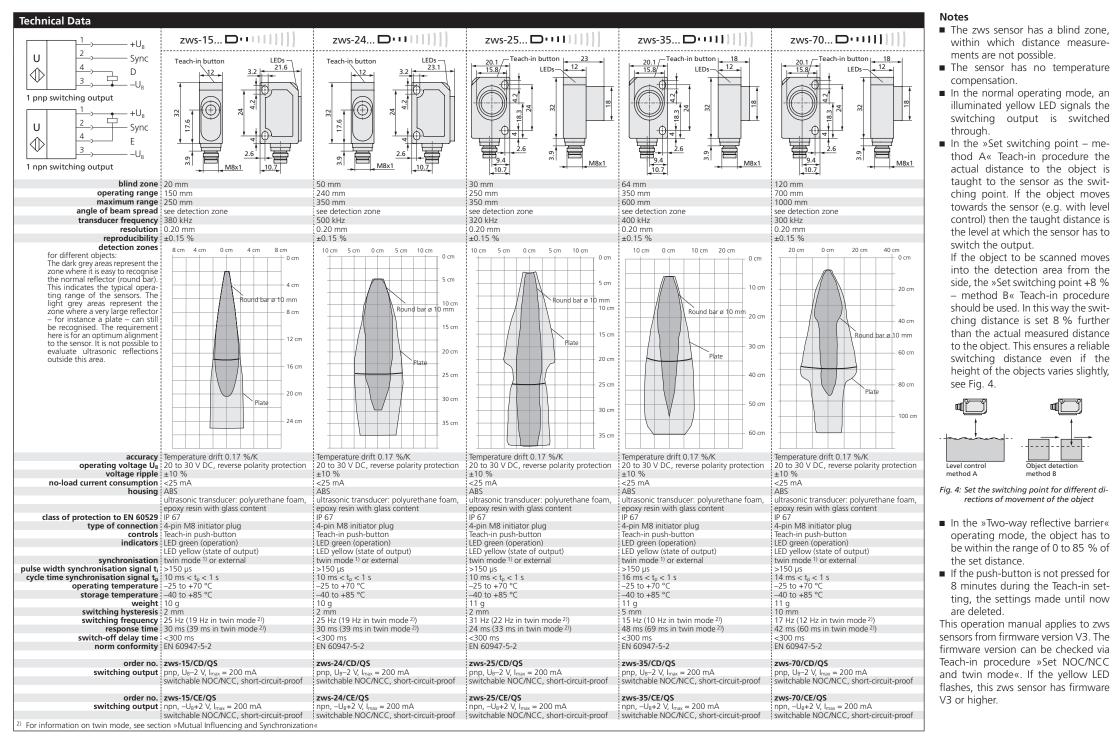
If two or more sensors are mounted too close to one another and the minimum assembly distances (see Fig. 3) between the sensors are not reached they can influence one another. There are two methods available to avoid this.

- If only two sensors are operating, the twin mode can be selected at one of the two sensors via the sensor setting »Set NOC/NCC and twin mode«. The other sensor stays at the standard NOC/NCC setting. For the sensor in twin mode, response delay is slightly increased und therefore the switching frequency reduced.
- If more than two sensors are operating close to one another, the sensors can be synchronised by the accessory SyncBox2.

	D ↓	D↔Q
zws-15	≥0.25 m	≥1.30 m
zws-24	≥0.25 m	≥1.40 m
zws-25	≥0.35 m	≥2.50 m
zws-35	≥0.40 m	≥2.50 m
zws-70	≥0.70 m	≥4.00 m
Fig. 3: Minimun	n assembly dista	nces for Sync

# Maintenance

microsonic sensors are maintenancefree. In case of excess caked-on dirt we recommend cleaning the white sensor surface.





Object detection

method B

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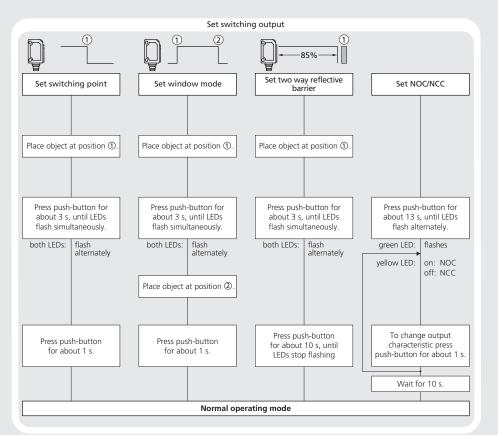


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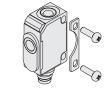
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#### Installation

- → Mount the sensor at the installation site with the aid of the enclosed mounting plate (see Fig. 1). Maximum torque of attachment screw: 0,5 Nm
- → Connect a connection cable to the M8 device plug.
- Avoid mechanical load on the connector.

## Start-Up

- → Connect the power supply.
- → Carry out the adjustment in accordance with Diagram 1.



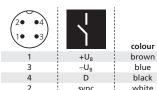


Fig. 2: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

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zws-sensors are delivered with the fol-

Operation with one switching point

Switching point at operating range

Three operating modes are available

Operation with one switching

The switching output is set if the

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Switching output on NOC

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Factory Setting

lowing settings:

**Operating modes** 

point

point.

Window mode

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## Synchronisation

You can synchronise as many sensors as you like.

- → Apply a square-wave signal to the sync-input with pulse width t<sub>i</sub> and repetition rate t<sub>p</sub> (Fig. 3 and technical data).
- A high level on the sync input will disable the sensor.

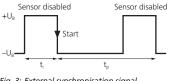


Fig. 3:	External	synchronisation	signal
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	P	
	Ď	D↔Q
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#### Maintenance

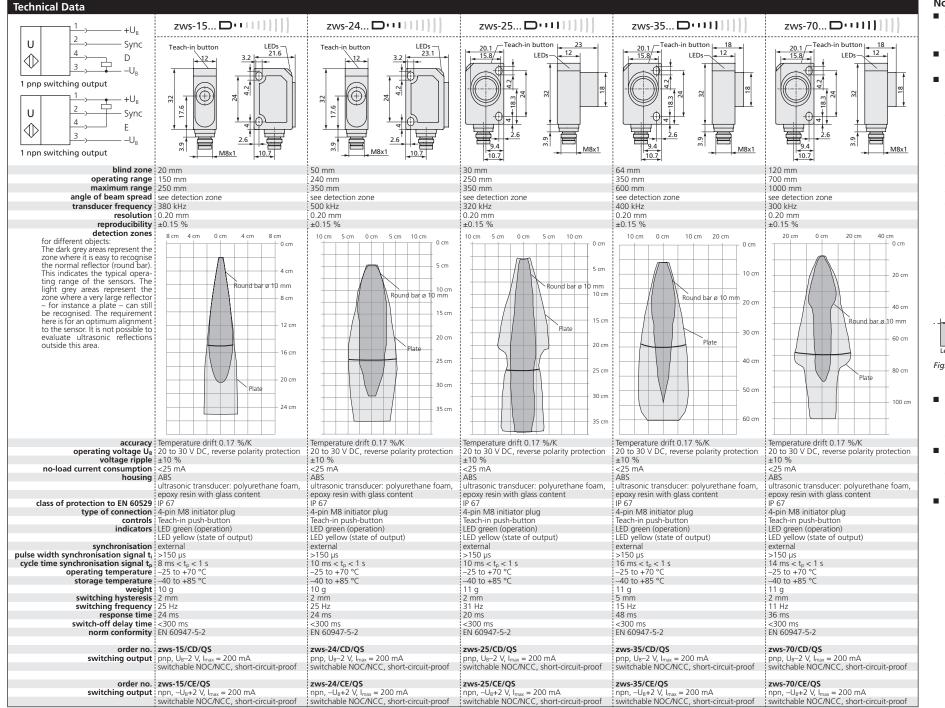
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Enable/disable Teach-in push-button		Reset to factory setting	
Starite	ch off	Swite	h off
operating voltage.		operating voltage.	
Press and hole	d push-button.	Press and hold	l push-button.
Switch on		Swite	h on
operating voltage.		operating	g voltage.
Keep push-button pressed for about 3 s until both LEDs flash simultaneously.		Keep push-button pressed for about 13 s until both LEDs stop flashing.	
green LED:	flashes		
yellow LED:	on: push-button enabled		
	off: push-button disabled		
	able Teach-in		
nress nue	sh-button		

Normal operating mode

Further settings

Fig. 1: Attachment with mounting plate



## Notes

- The zws sensor has a blind zone, within which distance measurements are not possible.
- The standard sensor has no temperature compensation.
- In the normal operating mode, an illuminated yellow LED signals the switching output is switched through.

In the Teach-in procedure the actual distance to the object is taught to the sensor as the switching point. If the object moves towards the sensor (e.g. with level control) then the taught distance is the level at which the sensor has to switch the output. If the object to be scanned moves into the detection area from the side, an 8 to 10 % greater distance should be set for reliable object detection by the sensor, see Fig. 5.

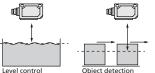


Fig. 5: Set the switching point for different directions of movement of the object

- In the »Two-way reflective barrier« operating mode, the object has to be within the range of 0 to 85 % of the set distance.
- If the push-button is not pressed for 10 minutes during the Teach-in setting, the settings made until now are deleted.
- The sensor can be reset to its factory setting, see »Further settings«, Diagram 1.

