



Operating Manual

mic Ultrasonic Sensors with one switching output

mic-25/D/M mic-35/D/M mic-130/D/M mic-340/D/M mic-600/D/M

Product description

The mic-sensor with one switching output measures the distance to an object within the detection zone contactless. Depending on the adjusted detect distance the switching output is set.

- The output functions are changeable from NOC to NCC.
- The sensors are adjustable using Teach-in processes via the Comchannel (Pin 5).
- Using the LinkControl adapter (optional accessory) all sensor parameter settings can be adjusted by a Windows[®] Software.

Safety Notes

- Read the operating instructions prior to start-up.
- Connection, installation and adjustment works may only be carried out by expert personnel.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted

The mic-sensors have a **blind zone** in which distance measurement is not possible. The **operating range** indicates the distance of the sensor that can be applied with normal reflectors with sufficient function reserve. When using good reflectors, such as a calm water surface, the sensor can also be used up to its **maximum range**. Objects that strongly absorb (e.g. plastic foam) or diffusely reflect sound (e.g. pebble stones) can also reduce the defined operating range.

Installation

- Assemble the sensor at the installation location.
- → Plug in the connector cable to the M12 connector, see Fig. 1.

| | | colour |
|---|-----------------|--------|
| 1 | +U _B | brown |
| 3 | -U _B | blue |
| 4 | D | black |
| 2 | - | white |
| 5 | Com | arev |

Fig. 1: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

Start-up

- → Connect the power supply.
- → Set detect points via the Teach-in procedure (see Diagram 1)

Factory setting

mic-sensors are delivered factorymade with the following settings:Switching output on NOC

- Detecting distance at operating ran-
- ge and half operating range Maximum detection range set to
- maximum range

Synchronisation

If the assembly distance of multiple sensors falls below the values shown in Fig. 2 the integrated synchronisation should be used. Connect Sync/ Com-channels (pin 5 at the units receptable) of all sensors (10 maximum).

Maintenance

mic-sensors work maintenance free. Small amounts of dirt on the surface do not influence function. Thick layers of dirt and caked-on dirt affect sensor function and therefore must be removed.

Notes

- mic-sensors have internal temperature compensation. Because the sensors heat up on their own, the temperature compensation reaches its optimum working point after approx. 30 minutes of operation.
 During Teach-in mode, the hystere-
- builting lead in mode, the hysteresis loops are set back to factory settings.
 If no signal is detected for 20 settings.
- conds during Teach-in procedure the made changes are stored and the sensor returns to normal mode operation.
- You can reset the factory settings at any time, see Diagram 2.

| | ₽ | |
|---------|---------|----------|
| | Ď | D↔Q |
| mic-25 | ≥0.35 m | ≥2.50 m |
| mic-35 | ≥0.40 m | ≥2.50 m |
| mic-130 | ≥1.10 m | ≥8.00 m |
| mic-340 | ≥2.00 m | ≥18.00 m |
| mic-600 | ≥4.00 m | ≥30.00 m |

Fig. 2: Assembly distances, indicating synchronisation

Teach-in switching output (1) (2) (1) Set two way reflective barrier Set switching point Set window limits Set NOC/NCC Place object at position ①. Place object at position ①. Place reflector at position ①. Connect Com to +U_n Connect Com to +U_n Connect Com to +U_a Connect Com to +U_n for about 3 s. for about 3 s. for about 3 s. for about 13 s. Place object at position ②. To change output characteristic Connect Com to +U_o Connect Com to +U_o Connect Com to +U_o connect Com to +U. for about 1 s. for about 1 s. for about 10 s. for about 10 s. Wait for 10 s.

Normal operating mode

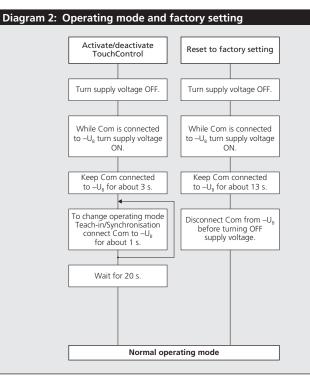
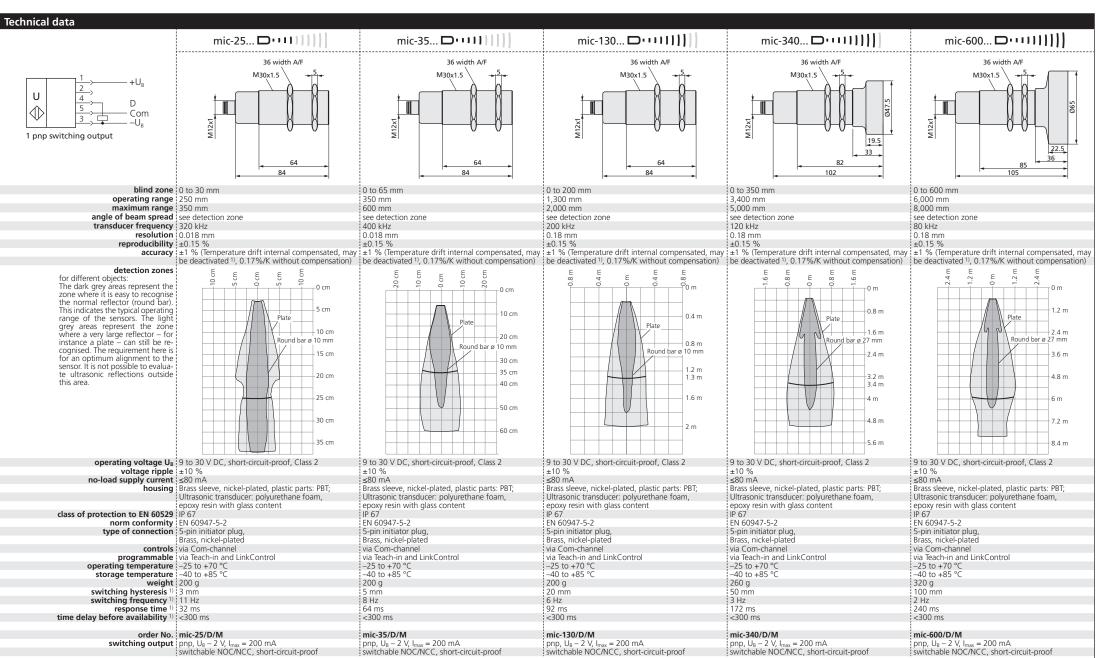


Diagram 1: Set sensor parameters via Teach-in procedure



¹⁾ Can be programmed via LinkControl.





