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**Operating Manual** 

mic Ultrasonic Sensors with one switching output

mic-25/D/M mic-35/D/M mic-130/D/M mic-340/D/M mic-600/D/M

## Product description

The mic-sensor with one switching output measures the distance to an object within the detection zone contactless. Depending on the adjusted detect distance the switching output is set.

- The output functions are changeable from NOC to NCC.
- The sensors are adjustable using Teach-in processes via the Comchannel (Pin 5).
- Using the LinkControl adapter (optional accessory) all sensor parameter settings can be adjusted by a Windows<sup>®</sup> Software.

#### Safety Notes

- Read the operating instructions prior to start-up.
- Connection, installation and adjustment works may only be carried out by expert personnel.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted

The mic-sensors have a **blind zone** in which distance measurement is not possible. The **operating range** indicates the distance of the sensor that can be applied with normal reflectors with sufficient function reserve. When using good reflectors, such as a calm water surface, the sensor can also be used up to its **maximum range**. Objects that strongly absorb (e.g. plastic foam) or diffusely reflect sound (e.g. pebble stones) can also reduce the defined operating range.

#### Installation

- Assemble the sensor at the installation location.
- → Plug in the connector cable to the M12 connector, see Fig. 1.

		colour
1	+U <sub>B</sub>	brown
3	-U <sub>B</sub>	blue
4	D	black
2	-	white
5	Com	arev

Fig. 1: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

#### Start-up

- → Connect the power supply.
- → Set detect points via the Teach-in procedure (see Diagram 1)

#### **Factory setting**

mic-sensors are delivered factorymade with the following settings:Switching output on NOC

- Detecting distance at operating ran-
- ge and half operating range Maximum detection range set to
- maximum range

#### Synchronisation

If the assembly distance of multiple sensors falls below the values shown in Fig. 2 the integrated synchronisation should be used. Connect Sync/ Com-channels (pin 5 at the units receptable) of all sensors (10 maximum).

#### Maintenance

mic-sensors work maintenance free. Small amounts of dirt on the surface do not influence function. Thick layers of dirt and caked-on dirt affect sensor function and therefore must be removed.

#### Notes

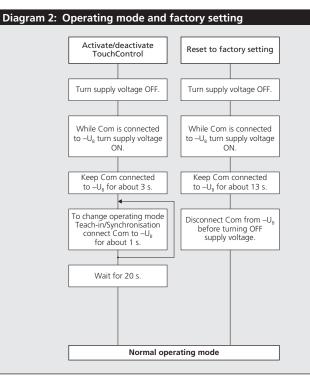
- mic-sensors have internal temperature compensation. Because the sensors heat up on their own, the temperature compensation reaches its optimum working point after approx. 30 minutes of operation.
  During Teach-in mode, the hystere-
- builting lead in mode, the hysteresis loops are set back to factory settings.
  If no signal is detected for 20 settings.
- conds during Teach-in procedure the made changes are stored and the sensor returns to normal mode operation.
- You can reset the factory settings at any time, see Diagram 2.

	₽	
	Ď	D↔Q
mic-25	≥0.35 m	≥2.50 m
mic-35	≥0.40 m	≥2.50 m
mic-130	≥1.10 m	≥8.00 m
mic-340	≥2.00 m	≥18.00 m
mic-600	≥4.00 m	≥30.00 m

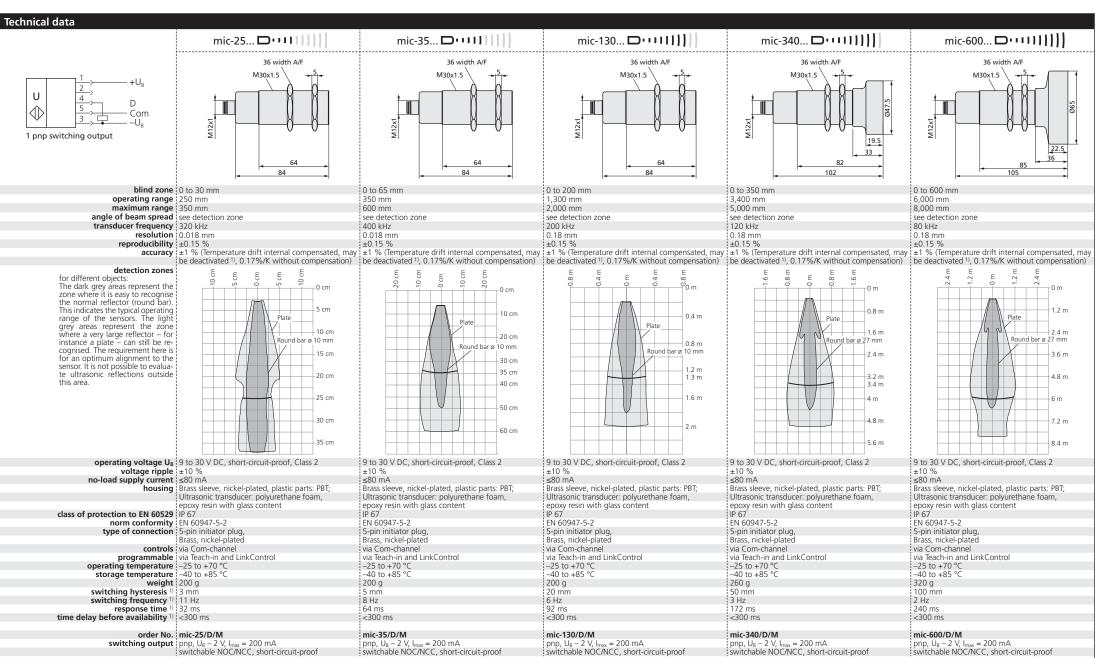
Fig. 2: Assembly distances, indicating synchronisation

#### Teach-in switching output (1) (2) (1) Set two way reflective barrier Set switching point Set window limits Set NOC/NCC Place object at position ①. Place object at position ①. Place reflector at position ①. Connect Com to +U<sub>n</sub> Connect Com to +U<sub>n</sub> Connect Com to +U<sub>a</sub> Connect Com to +U<sub>n</sub> for about 3 s. for about 3 s. for about 3 s. for about 13 s. Place object at position ②. To change output characteristic Connect Com to +U<sub>o</sub> Connect Com to +U<sub>o</sub> Connect Com to +U<sub>o</sub> connect Com to +U. for about 1 s. for about 1 s. for about 10 s. for about 10 s. Wait for 10 s.

Normal operating mode



### Diagram 1: Set sensor parameters via Teach-in procedure



<sup>1)</sup> Can be programmed via LinkControl.





