# wictotolic



Operating Manual mic Ultrasonic Sensors with one analogue output

mic-25/IU/M mic-35/IU/M mic-130/IU/M mic-340/IU/M mic-600/IU/M

#### Product description

- The mic-sensor with one analogue output measures the distance to an object within the detection zone contactless. A signal proportional to distance is created according to the adjusted window limits of the analogue characteristic curve.
- The sensor automatically detects the load put to the analogue output and switches to current output or voltage output respectively.
- Choosing between rising and falling output characteristic is possible.
- The sensors are adjustable using Teach-in processes via the Comchannel (Pin 5).
- Using the LinkControl adapter (optional accessory) all sensor parameter settings can be adjusted by a Windows® Software.

### Safety Notes

- Read the operating instructions prior to start-up.
- Connection, installation and adjustment works may only be carried out by expert personnel.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted

The mic-sensors have a **blind zone** in which distance measurement is not possible. The **operating range** indicates the distance of the sensor that can be applied with normal reflectors with sufficient function reserve. When using good reflectors, such as a calm water surface, the sensor can also be used up to its **maximum range**. Objects that strongly absorb (e.g. plastic foam) or diffusely reflect sound (e.g. pebble stones) can also reduce the defined operating range.

#### Installation

- → Assemble the sensor at the installation location.
- → Plug in the connector cable to the M12 connector, see Fig. 1.

2 • 1 3 • 5 • 4		colour
1	+U <sub>B</sub>	brown
3	−U <sub>B</sub>	blue
4	-	black
2	I/U	white
5	Com	grey

Fig. 1: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

#### Start-up

- → Connect the power supply.
- → Set sensor parameters via the Teach-in procedure (see Diagram 1)

#### Factory setting

mic-sensors are delivered factory made with the following settings:

- Rising analogue characteristic
- Window limits for the analogue output set to blind zone and operating range
- Maximum detection range set to maximum range

## Synchronisation

If the assembly distance of multiple sensors falls below the values shown in Fig. 2 the integrated synchronisation should be used. Connect Sync/Com-channels (pin 5 at the units receptable) of all sensors (10 maximum).

	₽	
	Ď	□⊶□
mic-25	≥0.35 m	≥2.50 m
mic-35	≥0.40 m	≥2.50 m
mic-130	≥1.10 m	≥8.00 m
mic-340	≥2.00 m	≥18.00 m
mic-600	≥4.00 m	≥30.00 m

Fig. 2: Assembly distances, indicating synchronisation

#### Maintenance

mic-sensors work maintenance free. Small amounts of dirt on the surface do not influence function. Thick layers of dirt and caked-on dirt affect sensor function and therefore must be removed.

#### Notes

- mic-sensors have internal temperature compensation. Because the sensors heat up on their own, the temperature compensation reaches its optimum working point after approx. 30 minutes of operation.
- The load put to the analogue output is detected automatically when turning supply voltage on.
- If no signal is detected for 20 seconds during teach-in procedure the made changes are stored and the sensor returns to normal mode operation.
- You can reset the factory settings at any time, see Diagram 1.

# Diagram 1: Set sensor parameters via Teach-in procedure











