MICLOYOUIC



Operating Manual

mic Ultrasonic Sensors with two switching outputs

mic-25/DD/M mic-35/DD/M mic-130/DD/M mic-340/DD/M mic-600/DD/M

Product description

The mic-sensor with two switching outputs measures the distance to an object within the detection zone contactless. Depending on the adjusted detect distances the switching outputs are set. The output functions are changeable from NOC to NCC.

Using the LinkControl adapter (optional accessory) all sensor parameter settings can be adjusted by a Windows® Software.

Safety Notes

- Read the operating manual prior to start-up.
- Connection, installation and adjustment works may only be carried out by expert personnel.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted

The mic-sensors have a **blind zone** in which distance measurement is not possible. The **operating range** indicates the distance of the sensor that can be applied with normal reflectors with sufficient function reserve. When using good reflectors, such as a calm water surface, the sensor can also be used up to its **maximum range**. Objects that strongly absorb (e.g. plastic foam) or diffusely reflect sound (e.g. pebble stones) can also reduce the defined operating range.

Installation

- → Assemble the sensor at the installation location.
- → Plug in the connector cable to the M12 connector, see Fig. 1.

| 2 • 1 3 • 5 • 4 | | colour |
|--------------------|-----------------|--------|
| 1 | +U _B | brown |
| 3 | –U _B | blue |
| 4 | D2 | black |
| 2 | D1 | white |
| 5 | Sync/Com | grey |

Fig. 1: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

Start-up

- → Connect the power supply.
- Set the parameters of the sensor using the LinkControl adapter LCA-2 with the LinkControl software.

Factory setting

mic-sensors are delivered factory made with the following settings:

- Switching outputs on NOC
- Detecting distances at operating range and half operating range
- Maximum detection range set to maximum range

Synchronisation

If the assembly distances shown in Fig. 2 for two or more sensors are exceeded the integrated synchronisation should be used. Connect pins 5 (Sync/ Com) of all sensors (10 maximum).

| | P | |
|---------|--------|--------|
| | Ď | D↔Q |
| mic-25 | <10 cm | <1.0 m |
| mic-35 | <30 cm | <1.7 m |
| mic-130 | <60 cm | <5.4 m |
| mic-340 | <1.6 m | <16 m |
| mic-600 | <2.6 m | <30 m |

Fig. 2: Assembly distances, indicating synchronisation/multiplex

Multiplex mode

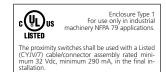
The sensors that are electrically connected to each other via pin 5 (Sync/ Com) can additionally be assigned an individual device address between »01« and »10« with LinkControl. The sensors then alternate with their ultrasonic measurements during operation in ascending order of the device addresses. This completely avoids mutual interference between the sensors. The device address »00« is reserved for synchronous operation and deactivates multiplex operation. For synchronous operation, all sensors must have the device address »00«.

Maintenance

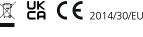
mic-sensors work maintenance free. Small amounts of dirt on the surface do not influence function. Thick layers of dirt and caked-on dirt affect sensor function and therefore must be removed.

Note

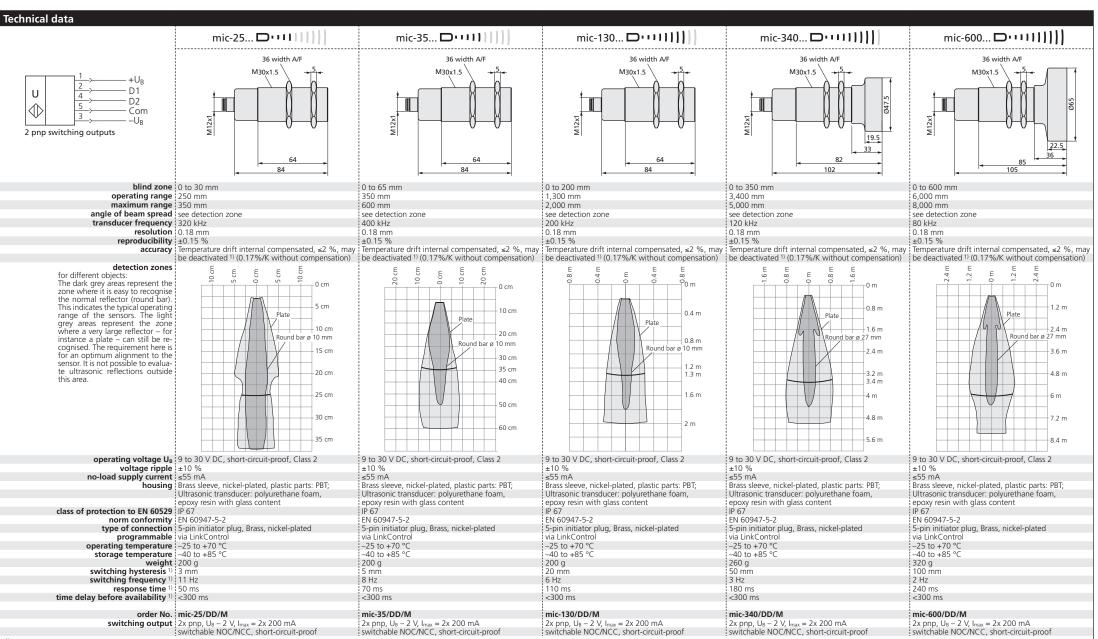
mic sensors have an internal temperature compensation. Due to the sensor's self-heating, the temperature compensation reaches its optimum operating point after approx. 30 minutes of operation.











¹⁾ Can be programmed via LinkControl.