microsonic

Operating Manual

pico+15/I	**pico+15/WK/I**
pico+25/I	**pico+25/WK/I**
pico+35/I	**pico+35/WK/I**
pico+100/I	**pico+100/WK/I**
pico+15/U	**pico+15/WK/U**
pico+25/U	**pico+25/WK/U**
pico+35/U	**pico+35/WK/U**
pico+100/U	**pico+100/WK/U**

Ultrasonic sensor with one analogue output

Product Description

The pico+ sensor offers a non-contact measurement of the distance to an object that has to be present within the sensor's detection zone. Depending on the set window limits, a distance-proportional analogue signal is output.
The window limits of the analogue output and its characteristic can be adjusted via Teach-in procedure. Two LEDs indicate the state of the analogue output.

Safety Notes

- Read the operating manual prior to start-up.
- Connection, installation and adjustment works should be carried out by expert personnel only.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted

Proper Use

pico+ ultrasonic sensors are used for non-contact detection of objects.

Installation

➔ Mount the sensor at the installation site.
➔ Connect a connection cable to the M12 device plug, see Fig. 1.

		colour
1	$+U_B$	brown
3	$-U_B$	blue
4	–	black
2	I/U	white
5	Com	grey

Fig. 1: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

Start-Up

➔ Connect the power supply.
➔ Set the sensor parameters using the Teach-in procedure, see Diagram 1.

Factory Setting

pico+ sensors are delivered factory made with the following settings:

- Rising analogue characteristic curve between the blind zone and the operating range
- Multifunctional input »Com« set to »Teach-in«

Synchronisation

If the assembly distance falls below the values shown in fig. 2, the internal synchronization should be used. For this purpose set the switched outputs of all sensors in accordance to the diagram »Sensor adjustment with Teach-in procedure« at first. Then set the multifunctional output »Com« to »synchronization« (see »Further settings«, Diagram 1). Finally connect pin 5 of the sensors plug of all sensors.

Maintenance

microsonic sensors are maintenance-free. In case of excess caked-on dirt we recommend to clean the white sensor surface.

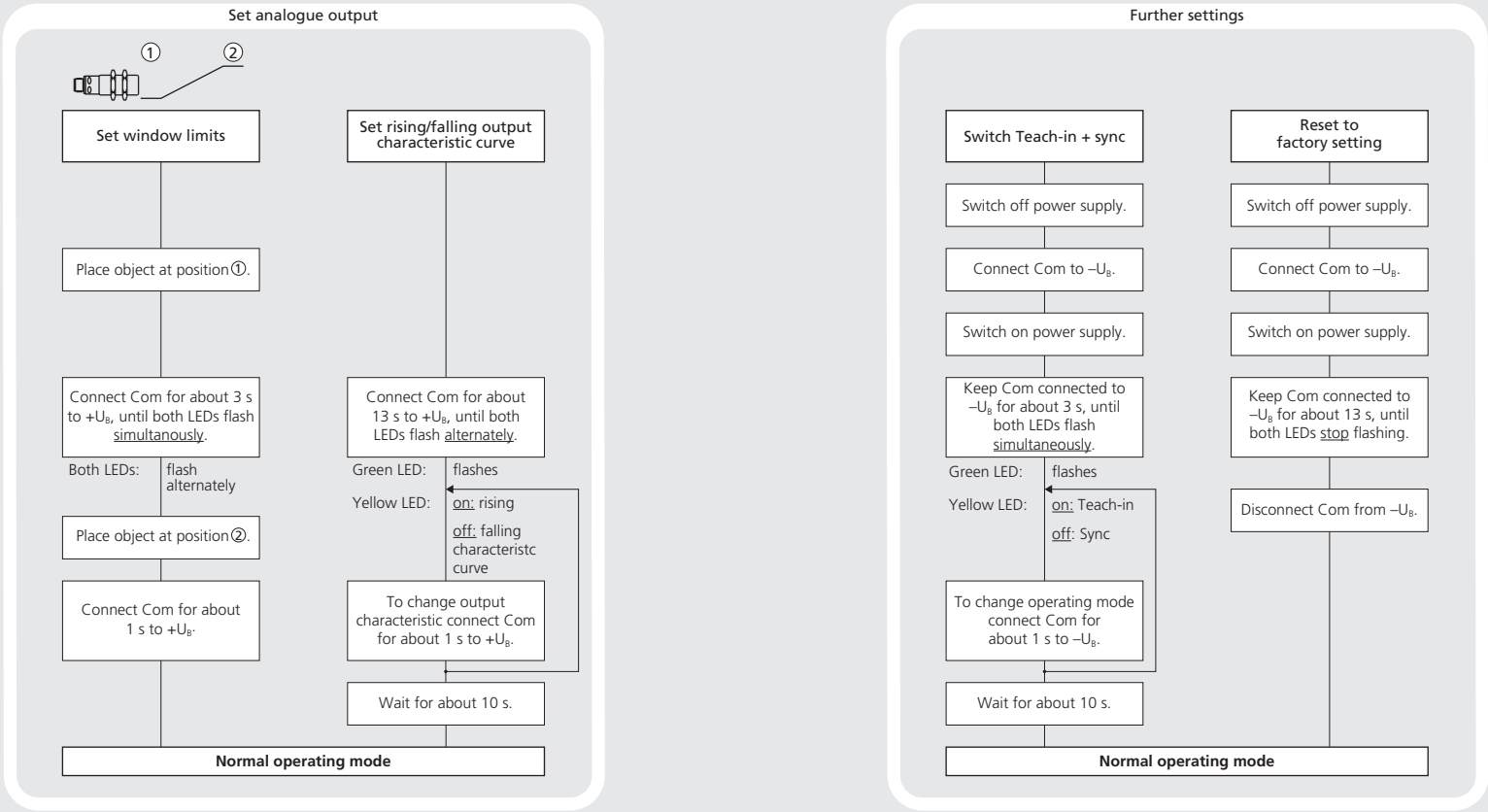
pico+15...	≥0.25 m	≥1.30 m
pico+25...	≥0.35 m	≥2.50 m
pico+35...	≥0.40 m	≥2.50 m
pico+100...	≥0.70 m	≥4.00 m

Fig. 2: Assembly distances, indication synchronisation

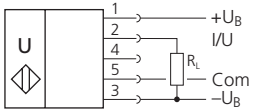
Notes

- The sensors of the pico+ family have a blind zone. Within this zone a distance measurement is not possible.
- Every time the power supply is switched on, the sensor detects its actual operating temperature and transmits it to the internal temperature compensation. The adjusted value is taken over after 120 seconds.
- In the normal operating mode, an illuminated yellow LED signals the object is within the window limits.
- If synchronisation is activated the Teach-in is disabled (see »Further settings«, Diagram 1).
- The sensor can be reset to its factory setting (see »Further settings«, Diagram 1).
- Optionally all Teach-in and additional sensor parameter settings can be adjusted via the LinkControl adapter (optional accessory) and the LinkControl software for Windows©.

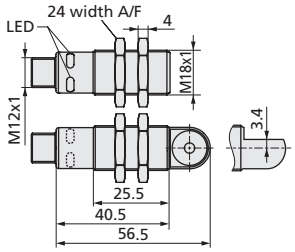
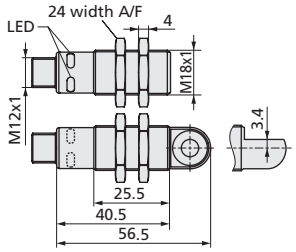
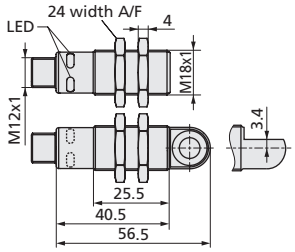
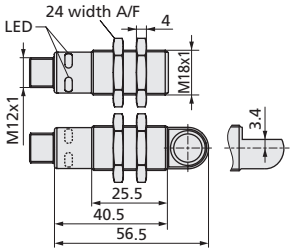
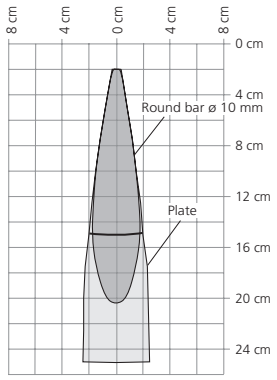
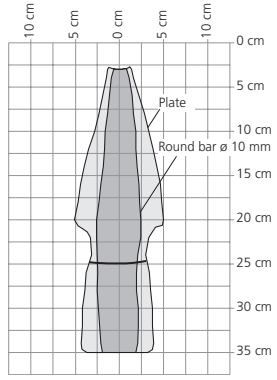
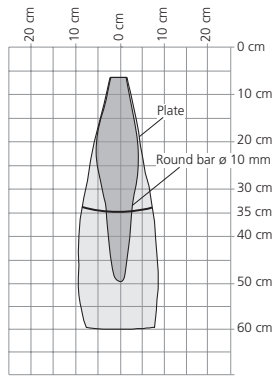
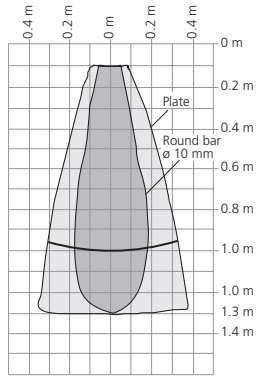
Diagram 1: Set sensor parameters via Teach-in procedure



Technical data



1 analogue output

	pico+15...	pico+25...	pico+35...	pico+100...
				
blind zone	20 mm	30 mm	65 mm	120 mm
operating range	150 mm	250 mm	350 mm	1.000 mm
maximum range	250 mm	350 mm	600 mm	1.300 mm
angle of beam spread	see detection zone	see detection zone	see detection zone	see detection zone
transducer frequency	380 kHz	320 kHz	400 kHz	200 kHz
resolution	0.069 mm	0.069 to 0.1 mm, depending on the analogue window	0.069 to 0.17 mm, depending on the analogue window	0.069 to 0.38 mm, depending on the analogue window
detection zones for different objects: The dark grey areas are determined with a round bar and indicate the typical operating range of a sensor. In order to obtain the light grey areas, a plate (100 x 100 mm) is introduced into the beam spread from the side. In doing so, the optimum angle between plate and sensor is always employed. This therefore indicates the maximum detection zone of the sensor. It is not possible to evaluate ultrasonic reflections outside this area.				
reproducibility	±0.15 %	±0.15 %	±0.15 %	±0.15 %
accuracy	±1 % (Temperature drift internal compensated)	±1 % (Temperature drift internal compensated)	±1 % (Temperature drift internal compensated)	±1 % (Temperature drift internal compensated)
no-load current consumption	<40 mA	<40 mA	<40 mA	<40 mA
operating voltage ripple	±10 %	±10 %	±10 %	±10 %
housing	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content
max. tightening torque of nuts	15 Nm	1 Nm	15 Nm	15 Nm
class of protection to EN 60529	IP 67	IP 67	IP 67	IP 67
norm conformity	EN 60947-5-2	EN 60947-5-2	EN 60947-5-2	EN 60947-5-2
type of connection	5-pin M12 initiator plug	5-pin M12 initiator plug	5-pin M12 initiator plug	5-pin M12 initiator plug
controls	Teach-in via pin 5 (Com)	Teach-in via pin 5 (Com)	Teach-in via pin 5 (Com)	Teach-in via pin 5 (Com)
scope for setting	Teach-in, LinkControl	Teach-in, LinkControl	Teach-in, LinkControl	Teach-in, LinkControl
indicators	LED green, LED yellow	LED green, LED yellow	LED green, LED yellow	LED green, LED yellow
synchronisation	internal synchronisation up to 10 sensors	internal synchronisation up to 10 sensors	internal synchronisation up to 10 sensors	internal synchronisation up to 10 sensors
operating temperature	–25 to +70 °C	–25 to +70 °C	–25 to +70 °C	–25 to +70 °C
storage temperature	–40 to +85 °C	–40 to +85 °C	–40 to +85 °C	–40 to +85 °C
response time [1]	32 ms	32 ms	64 ms	80 ms
time delay before availability	<300 ms	<300 ms	<300 ms	<300 ms
analogue output 4 to 20 mA	R_L ≤ 500 Ω, rising/falling characteristic	R_L ≤ 500 Ω, rising/falling characteristic	R_L ≤ 500 Ω, rising/falling characteristic	R_L ≤ 500 Ω, rising/falling characteristic
operating voltage U_B	10 to 30 V DC for R_L ≤ 100 Ω 20 to 30 V DC for R_L > 100 Ω terminal reverse polarity protected, Class 2	10 to 30 V DC for R_L ≤ 100 Ω 20 to 30 V DC for R_L > 100 Ω terminal reverse polarity protected, Class 2	10 to 30 V DC for R_L ≤ 100 Ω 20 to 30 V DC for R_L > 100 Ω terminal reverse polarity protected, Class 2	10 to 30 V DC for R_L ≤ 100 Ω 20 to 30 V DC for R_L > 100 Ω terminal reverse polarity protected, Class 2
order no. directly radiating	**pico+15/I**	**pico+25/I**	**pico+35/I**	**pico+100/I**
weight	30 g	30 g	30 g	30 g
order no. angular head	**pico+15/WK/I**	**pico+25/WK/I**	**pico+35/WK/I**	**pico+100/WK/I**
weight	35 g	35 g	35 g	35 g
analogue output 0 to 10 V	R_L ≥ 100 kΩ, short circuit proof, rising/falling characteristic	R_L ≥ 100 kΩ, short circuit proof, rising/falling characteristic	R_L ≥ 100 kΩ, short circuit proof, rising/falling characteristic	R_L ≥ 100 kΩ, short circuit proof, rising/falling characteristic
operating voltage U_B	15 to 30 V DC, terminal reverse polarity protected, Cl. 2	15 to 30 V DC, terminal reverse polarity protected, Cl. 2	15 to 30 V DC, terminal reverse polarity protected, Cl. 2	15 to 30 V DC, terminal reverse polarity protected, Cl. 2
order no. directly radiating	**pico+15/U**	**pico+25/U**	**pico+35/U**	**pico+100/U**
weight	30 g	30 g	30 g	30 g
order no. angular head	**pico+15/WK/U**	**pico+25/WK/U**	**pico+35/WK/U**	**pico+100/WK/U**
weight	35 g	35 g	35 g	35 g

[1] With LinkControl, the selected filter setting influences the response time.

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Enclosure Type 1
For use only in industrial machinery NFPA 79 applications.

The proximity switches shall be used with a Listed (CYJV/7) cable/connector assembly rated minimum 32 Vdc, minimum 290 mA, in the final installation.

microsonic GmbH / Phoenixseestraße 7 / 44263 Dortmund / Germany / T +49 231 975151-0 / **F** +49 231 975151-51 / **E** info@microsonic.de / **W** microsonic.de
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